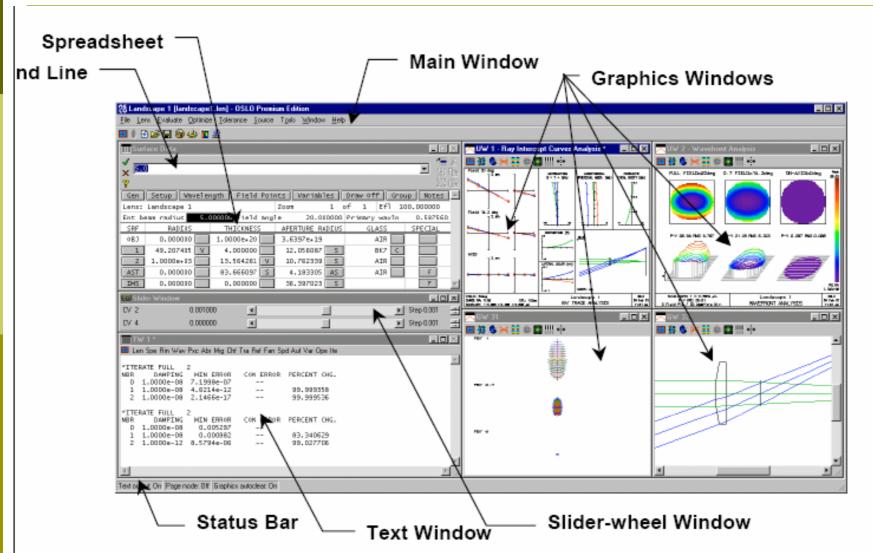
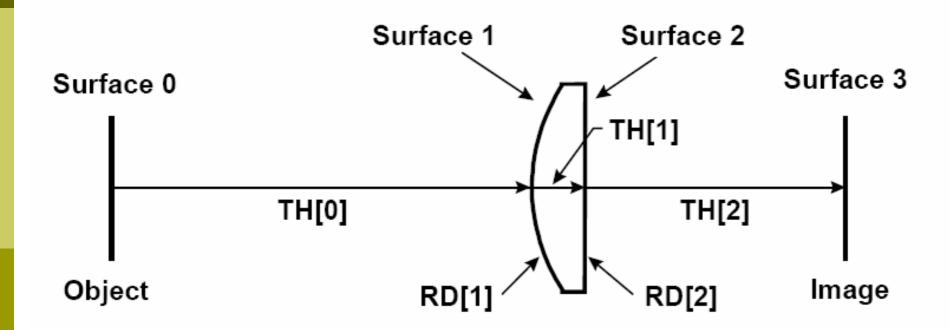
Introductory exercise for OSLO

A typical configuration of OSLO



Surface numbering



Sign conventions

Sign conventions for centered systems

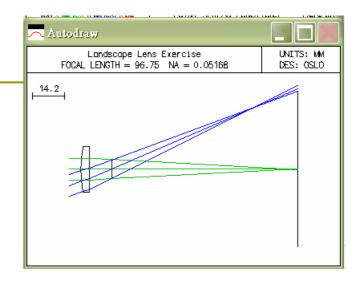
RADIUS OF CURVATURE	The radius of curvature, or curvature of a surface is positive if the center of curvature lies to the right of the surface.
THICKNESS	The thickness separating two surfaces is positive if the next surface lies to the right of the current surface; otherwise it is negative.
REFRACTIVE INDEX	OSLO expects all refractive indices to be provided with positive signs. Reflecting surfaces are specified explicitly by the designation, rfl.

Steps in the exercise

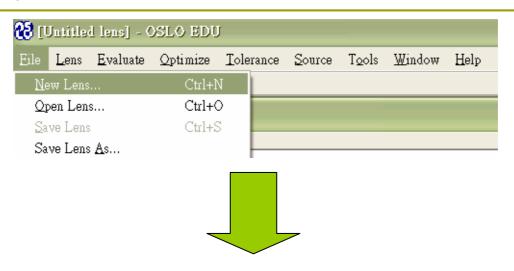
- Lens entry Enter a convex-plano lens with a displaced aperture stop behind the lens.
- Lens Drawing Set up the lens drawing conditions to show desired ray trajectories.
- Optimization Optimize the lens so it has no coma, a focal length of 100, and covers a field of ±20 degrees at an aperture of f/10.
- Slider-wheel design Attach sliders to parameters so you can analyze trade-offs.

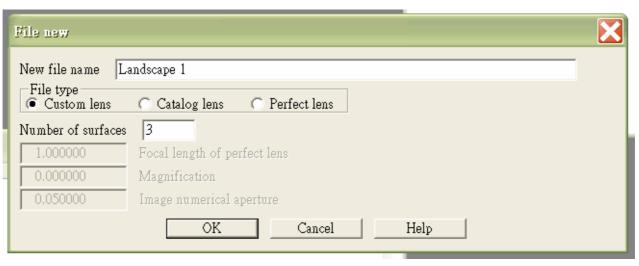
Lens entry, 1

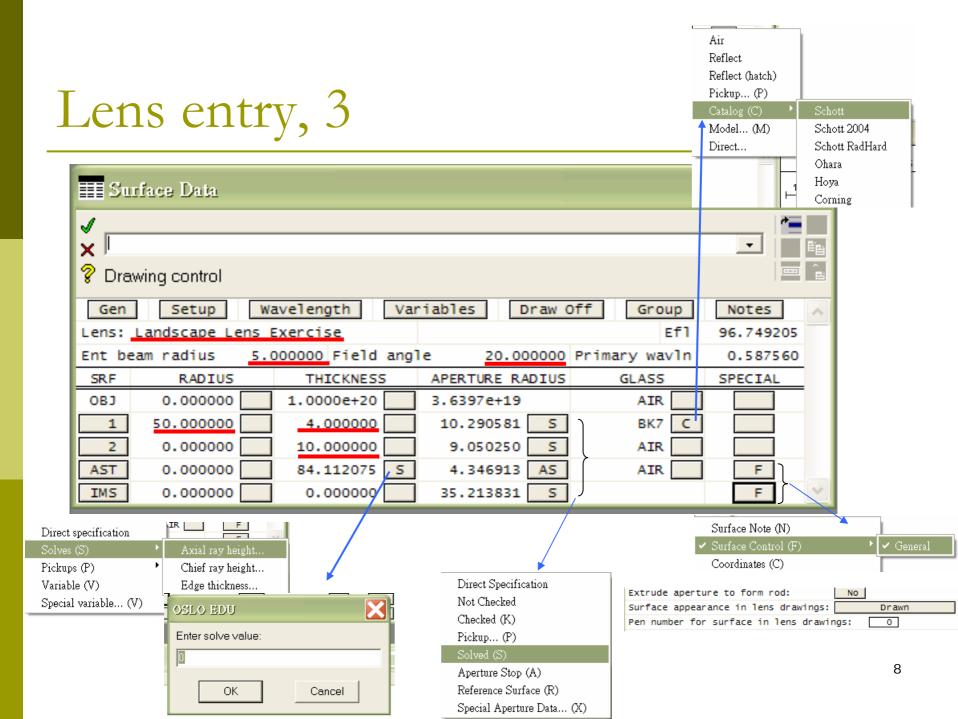
- beam radius = 5 mm
- □ field angle = 20 degree
- Convex-plano lens
 - Radius of surface 1= 50 mm
 - Radius of surface 2= 0 mm (∞)
 - Thickness=4 mm
 - Material = BK7
- Initial position of aperture stop=10 mm after the surface 2 of the convex-plano lens



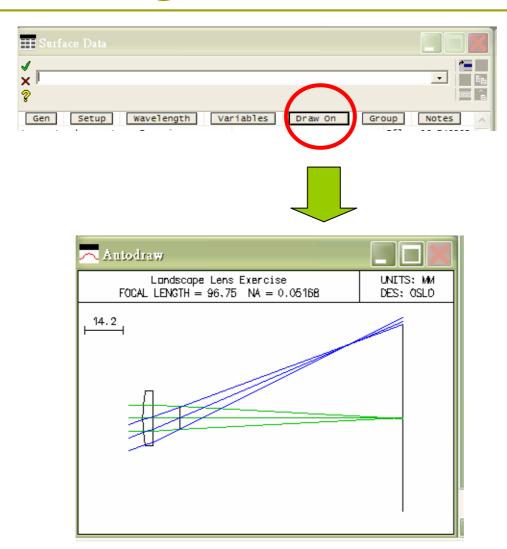
Lens entry, 2

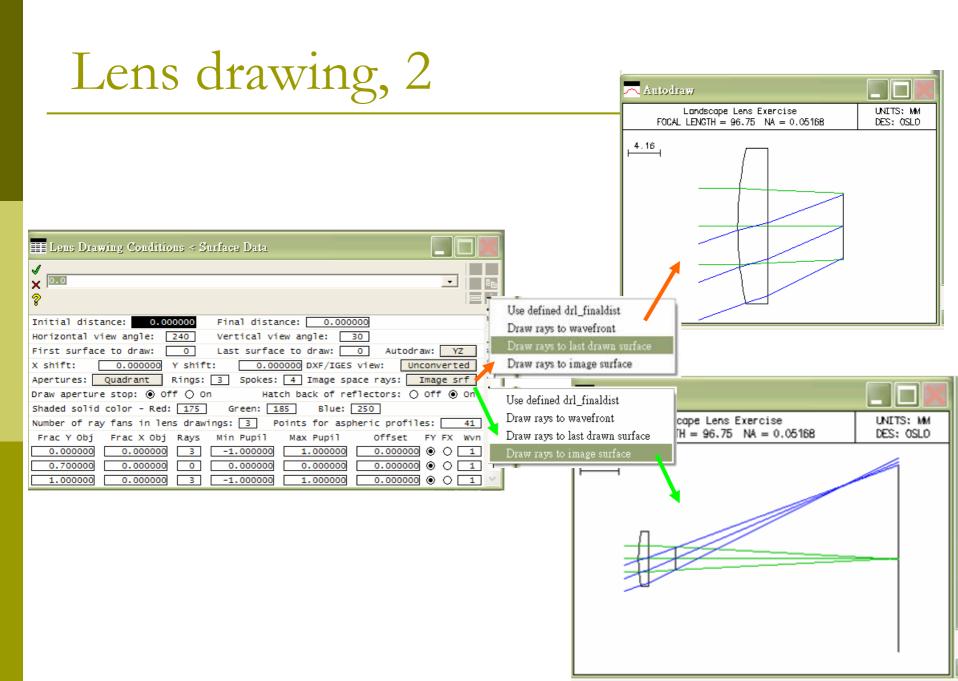




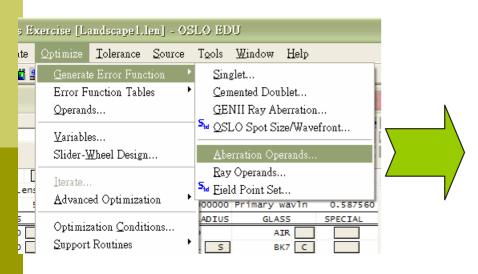


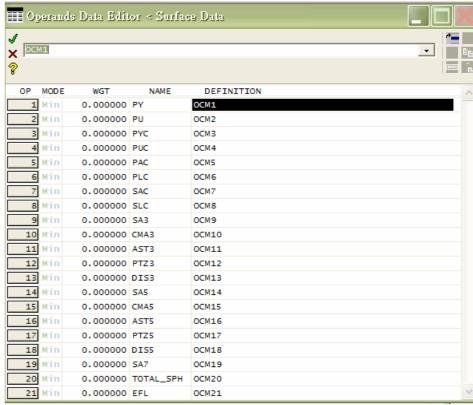
Lens drawing, 1





■ We will define an error function that makes the focal length exactly 100 mm, and also eliminates the Seidel coma from the image.





PU operand is the axial ray

→ slope leaving the lens.

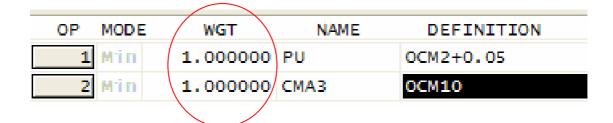
- 1					
	OP MODE	WGT	NAME	DEFINITION	
	1 Min	0.000000	PU	OCM2	
	2 Min	0.000000	CMA3 -	OCM10	Coma

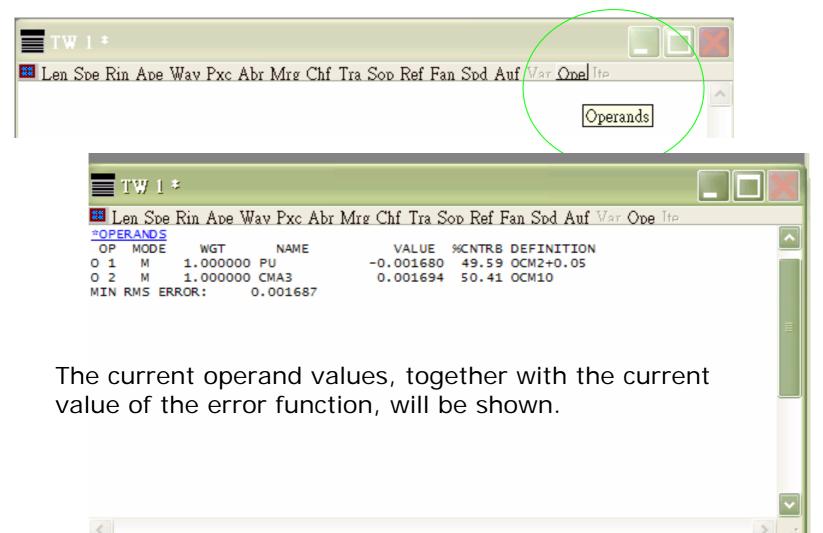
Beam radius = 5 mm Effective focal length=100mm

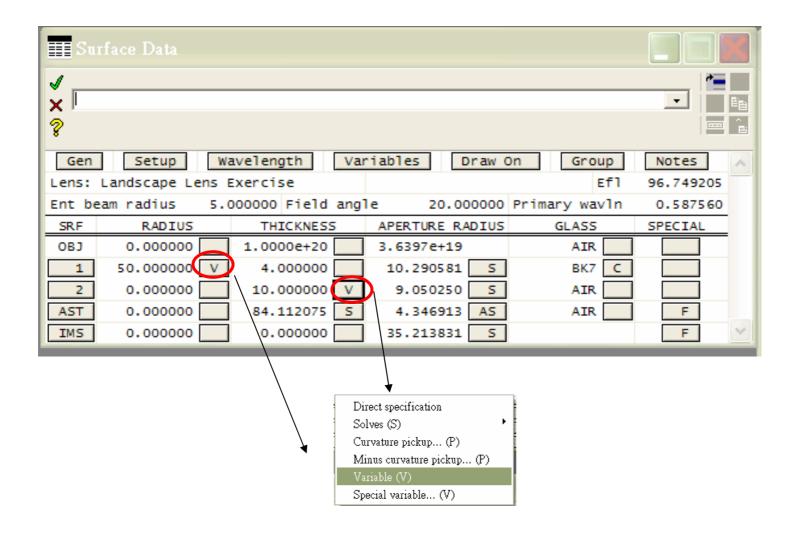


f-number = 10 PU=0.05 radian

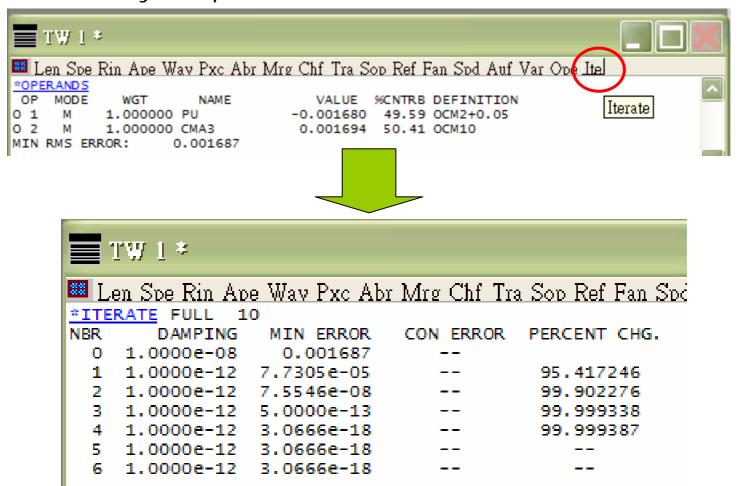
In OSLO, all operands are targeted to zero.



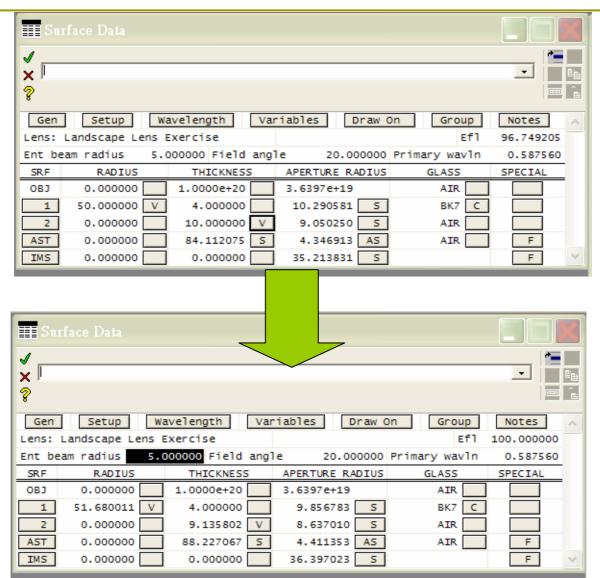


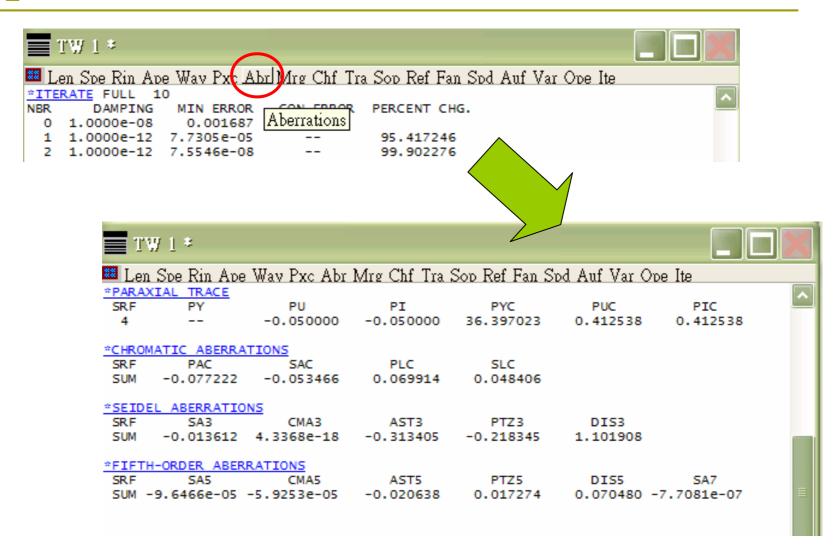


Before doing optimization, close the lens spreadsheet (Green check) and immediately re-open it.

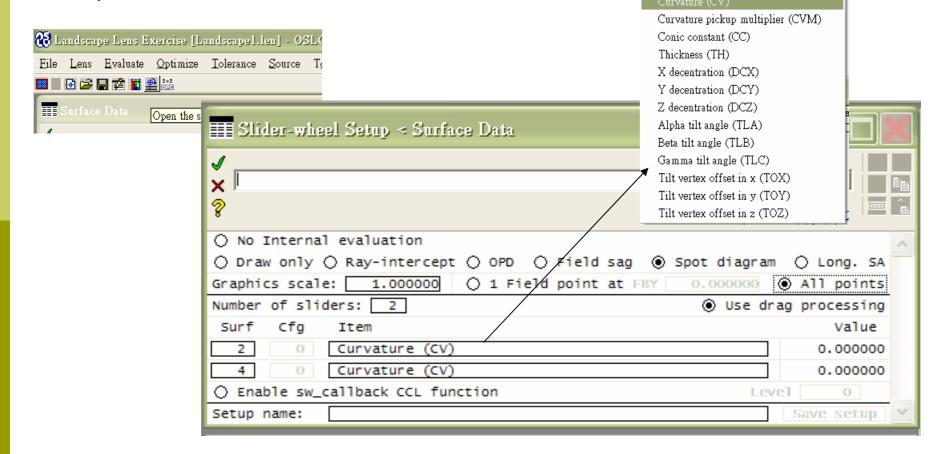


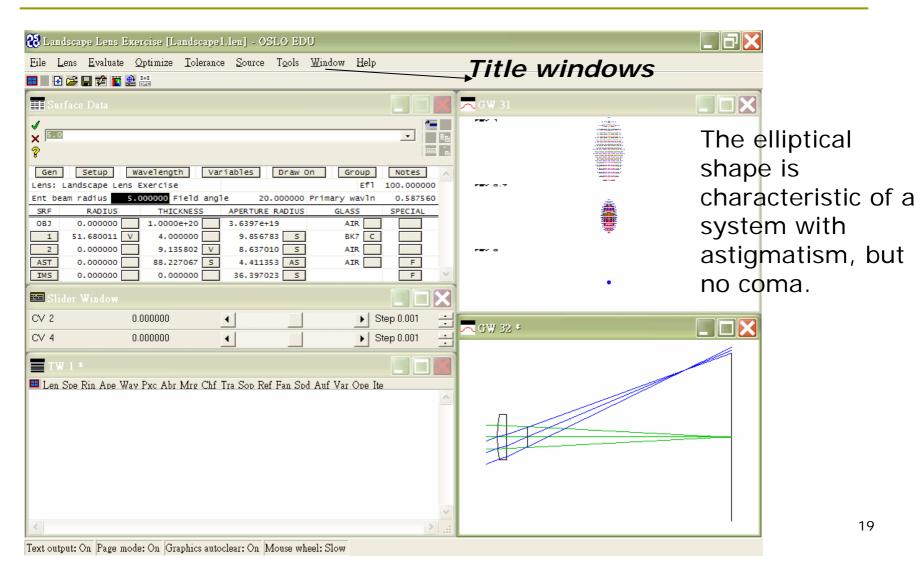
15

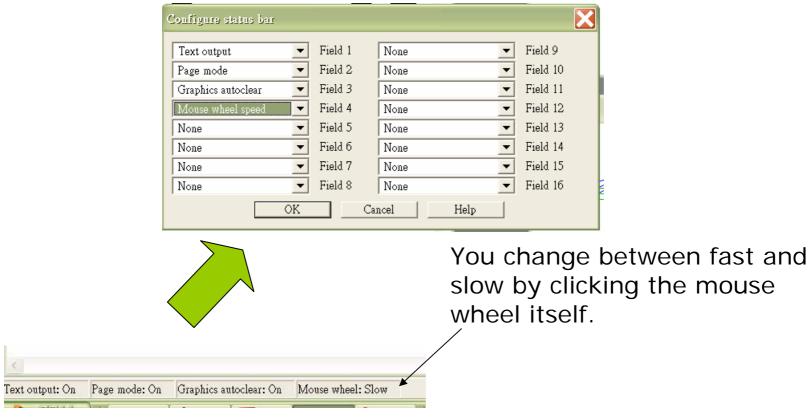




A landscape lens is normally a meniscus form. Next we show how to use OSLO's slider-wheel window to find the optimum form.

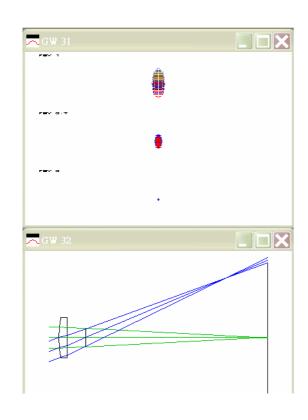


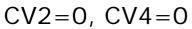


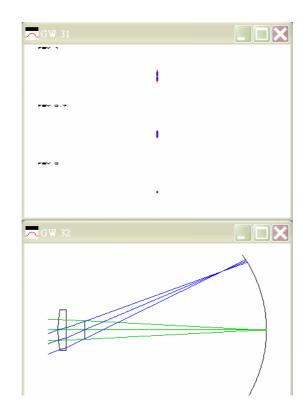


double click on the status bar in the main OSLO window.

- If you make CV[2] negative, the lens becomes positive and the focal length gets smaller. The image quality changes, since the system is no longer free of coma. If you make CV[2] positive, the lens becomes first a meniscus with a long focal length, but eventually the lens becomes negative.
- When you change CV[4], you see that by making it negative, you can improve the size of the image off-axis, and in fact you can find a position where there is a line focus in the horizontal direction (tangential focus), or the vertical direction (sagittal focus). This is indicative of a system with no coma.

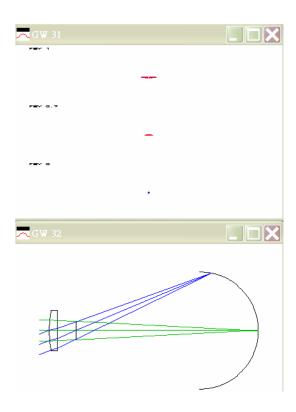






CV2=0, CV4=-0.016

sagittal focus

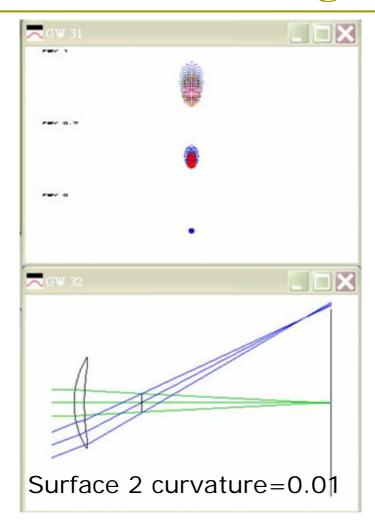


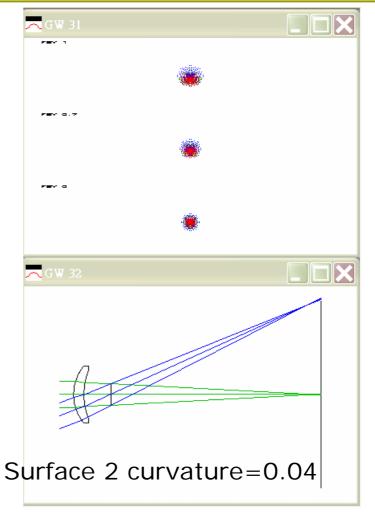
CV2=0, CV4=-0.035

tangential focuş₂

The real power of sliders in OSLO comes when you allow the program to re-optimize the system as you drag a slider.

Ⅲ Slider-wheel Setup < Surface Data	
○ No Internal evaluation ○ Draw only ○ Ray-intercept ○ OPD ○ Field sag ● Spot diagram Graphics scale: 1.000000 ○ 1 Field point at FBY 0.000000	O Long. SA All points
Surf Cfg Item	ag processing Value
2 0 Curvature (CV) 4 0 Curvature (CV) © Enable sw_callback CCL function Lev	0.000000 0.000000
Setup name:	Save setup





■ The stop initially moves away from the lens as it becomes a meniscus, but as the bending becomes larger, the stop shift reverses and the aperture stop moves back towards the lens.

Optical materials

The most important is often the dispersion, but many other attributes must also be considered, such as thermal characteristics, weight, mechanical and chemical properties, availability, and cost.

Dispersion, 1

Sellmeier formula

$$n^{2}(\lambda) = 1.0 + \frac{b_{1}\lambda^{2}}{\lambda^{2} - c_{1}} + \frac{b_{2}\lambda^{2}}{\lambda^{2} - c_{2}} + \frac{b_{3}\lambda^{2}}{\lambda^{2} - c_{3}}$$

Laurent series, sometimes called the Schott formula

$$n^{2}(\lambda) = A_{0} + A_{1}\lambda^{2} + \frac{A_{2}}{\lambda^{2}} + \frac{A_{3}}{\lambda^{4}} + \frac{A_{4}}{\lambda^{6}} + \frac{A_{5}}{\lambda^{8}}$$

• where λ is the wavelength in μ m.

Dispersion, 2

Conrady found that in the visible portion of the spectrum a good fit could be obtained using the formula

$$n(\lambda) = n_0 + \frac{A}{\lambda} + \frac{B}{\lambda^{3.5}}$$

■ **Buchdahl** introduced a *chromatic coordinate* for accurately characterizing the refractive index.

$$\omega(\lambda) = \frac{\lambda - \lambda_0}{1 + 2.5(\lambda - \lambda_0)}$$

$$n(\omega) = n_0 + v_1 \omega + v_2 \omega^2 + v_3 \omega^3 + \cdots$$

• where the wavelength λ is expressed in μ m and λ_0 is a reference wavelength, typically the d line (0.5876 μ m) for visible light.

V number or Abbe number

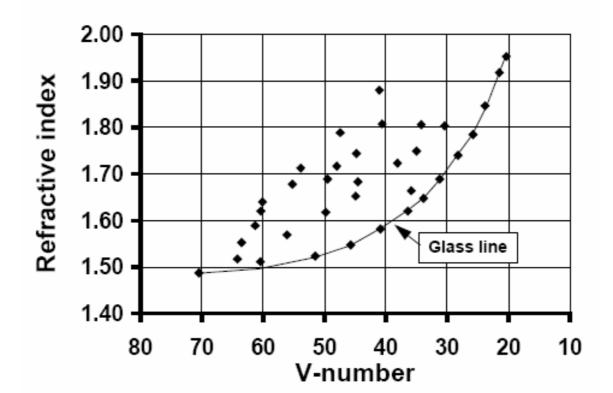
 $lue{}$ V (or ν) number, or Abbe number, is defined by

$$V \equiv \frac{n_d - 1}{n_F - n_C}$$

- n_d : the refractive index at the helium d (0.5876 μ m) line
- n_F : the refractive index at the hydrogen F (0.4861 μ m) line
- n_c : the refractive index at the hydrogen C (0.6563 μ m) line.
- In OSLO, wavelength 1 is taken to be the primary wavelength, wavelength 2 to be the short wavelength, and wavelength 3 to be the long wavelength.

Glass map, 1

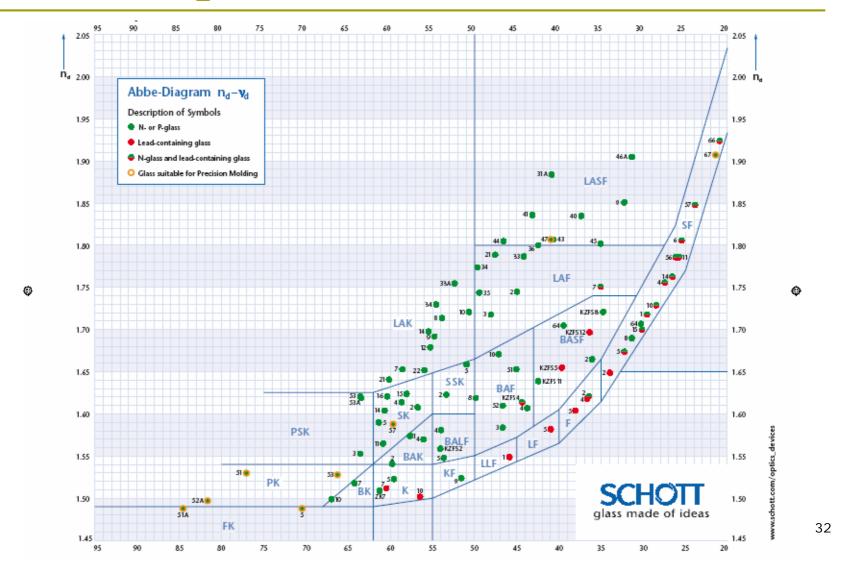
The characteristics of optical glasses are often displayed on a two-dimensional graph, called a glass map.



Glass map, 2

- Most glasses lie along or near a line forming the lower right boundary of the region occupied by optical glasses. This line is called the *glass line*.
- The availability of optical glasses that are located a considerable distance above the glass line gives the optical designer considerable flexibility in correcting the chromatic (and other) aberrations of optical systems.
- However, when an arbitrary choice is to be made, the glass chosen should be one on or near the glass line, since such glasses are cheaper and more readily available.

Glass map (Schott)

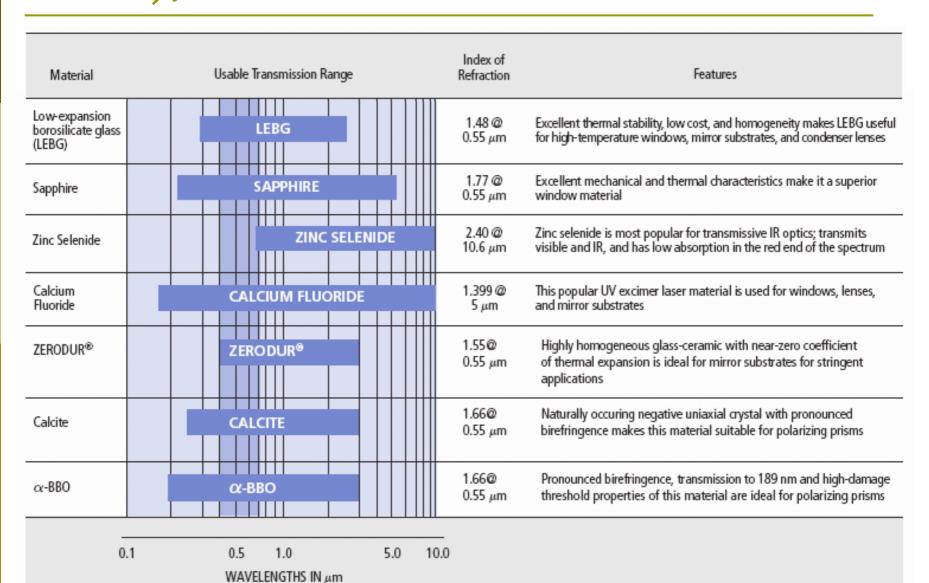


Material Properties Overview (Melles Griot), 1

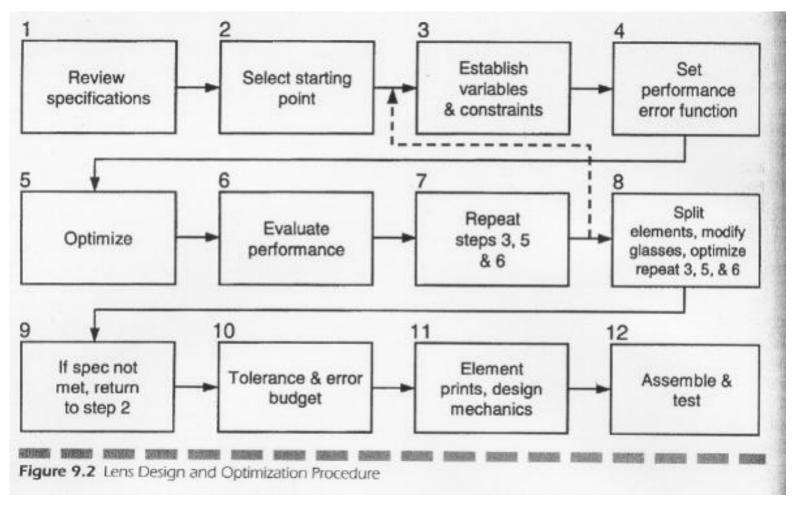
Material	Usable Transmission Range	Index of Refraction	Features
3K7 N-BK7	вк7	1.52 @ 0.55 μm	Excellent all-around lens material provides broad transmission with excellent mechanical characteristics
.aSFN9	LaSFN9	1.86 @ 0.55 μm	High-refractive-index flint glass provides more power with less curvature
F11	SF11	1.79 @ 0.55 μm	High-refractive-index flint glass provides more power with less curvature
-2	F2	1.62 @ 0.55 μm	Material represents a good compromise between higher index and acceptable mechanical characteristics
BaK1 N-BaK1	BaK1	1.57 @ 0.55 μm	Excellent all-around lens material, but has weaker chemical characteristics than BK7
Optical-Quality Synthetic Fused Silica OQSFS)	OQSFS	1.46 @ 0.55 μm	Material provides good UV transmission and superior mechanical characteristics
JV-Grade Synthetic Fused Silica UVGSFS)	UVGSFS	1.46 @ 0.55 μm	Material provides excellent UV transmission and superior mechanical characteristics
Optical Crown Glass	OPTICAL CROWN	1.52 @ 0.55 μm	This lower tolerance glass can be used as a mirror substrate or in non critical applications

WAVELENGTHS IN um

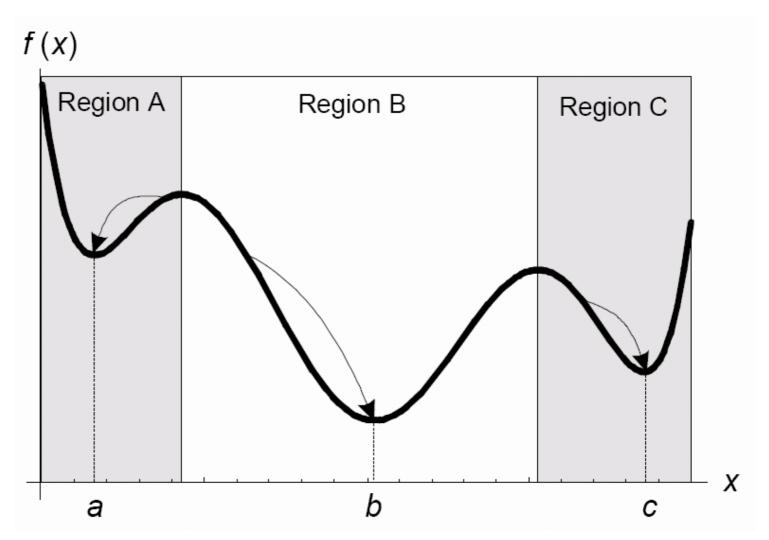
Material Properties Overview (Melles Griot), 1



Lens Design and Optimization Procedure



- optimization in optical design refers to the improvement of the performance of an optical system by changing the values of a subset of the system's constructional parameters (variables).
- The variables are quantities such as surface curvatures, element and air-space thicknesses, tilt angles, etc.
- The system's performance is measured by a user-defined error function, which is the weighted sum of squares of operands, that represents an estimate of the difference in performance between a given optical system and a system that meets all the design requirements.



Approach to optimization

- the user chooses initial values for the variables and an optimization algorithm is applied that repeatedly attempts to find new values for the variables that yield ever lower error function values.
- This approach depends heavily upon the choice of the starting point.
- Starting points are typically determined by experience or by finding an existing design with properties similar to those desired.
- Most of optimization methods employed in optical design are least-squares methods,

Default tolerances in OSLO

	Maximum dimension of part (mm)					
Property	Up to 10	Over 10 Up to 30	Over 30 Up to 100	Over 100 Up to 300		
Edge length, diameter (mm)	± 0.2	± 0.5	± 1.0	± 1.5		
Thickness (mm)	± 0.1	± 0.2	± 0.4	± 0.8		
Angle deviation of prisms and plate	± 30′	± 30′	± 30′	± 30'		
Width of protective chamfer (mm)	0.1 - 0.3	0.2 - 0.5	0.3 - 0.8	0.5 - 1.6		
Stress birefringence (nm/cm)	0/20	0/20	_	_		
Bubbles and inclusions	1/3 x 0.16	1/5x0.25	1/5x0.4	1/5x0.63		
Inhomogeneity and striae	2/1;1	2/1;1	_	_		
Surface form tolerances	3/5(1)	3/10(2)	3/10(2) 30 mm diameter	3/10(2) 60 mm diameter		
Centering tolerances	4/30′	4/20′	4/10′	4/10 ′		
Surface imperfection tolerances	5/3x0.16	5/5x0.25	5/5x0.4	5/5x0.63		

These tolerance values are taken from the ISO 10110 standard.

Typical optical fabrication tolerances

	Surface Quality	Diameter, mm	Deviation (concentricity) min	Thickness, mm	Radius	Regularity (asphericity)	Linear Dimension, mm	Angles
Low cost Commercial	120-80 80-50	± 0.2 ± 0.07	> 10 3–10	± 0.5 ± 0.25	Gage 10 Fr	Gage 3 Fr	± 0.5 ± 0.25	Degrees ± 15'
Precision Extraprecise Plastic	60-40 60-40 80-50	± 0.02 ± 0.01	1–3 < 1 1	± 0.1 ± 0.05 ± 0.02	5 Fr 1 Fr 10 Fr	1 Fr 1/5 Fr 5 Fr	± 0.1 As req'd. 0.02	± 5'-10' Seconds minutes

Ref: W. Smith, Optical modern engineering